

Estimation With Applications To Tracking And Navigation

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Estimation with Applications to Tracking and Navigation treats the estimation of various quantities from inherently inaccurate remote observations. It explains state estimator design using a balanced combination of linear systems, probability, and statistics. The authors provide a review of the necessary background mathematical techniques and offer an overview of the basic concepts in estimation.

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Estimation with Applications To Tracking and Navigation Yaakov Bar-Shalom X.-Rong Li Thiagalingam Kirubarajan A Wiley-Interscience Publication

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For decentralized tracking applications, distributed Kalman filtering and smoothing algorithms are derived for any-time MMSE optimal consensus-based state estimation using WSNs. Analysis and corroborating numerical examples demonstrate the merits of the novel distributed estimators.

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