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Ugur HALICI - METU EEE - ANKARA 11/18/2004 EE543 - ANN - CHAPTER 2 6 CHAPTER II : Recurrent Neural Networks 2. 4. Gradient, Conservative and Dissipative Systems Level surfaces If we set E(x)=c, we obtain a family of surfaces known as level surfacesof E, as x takes on different values. On the assumption that E is single valued at each point, one and only one level surface passes through any given

~~CHAPTER II~~
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Ugur HALICI - METU EEE - ANKARA 11/18/2004 EE543 - ANN - CHAPTER 4 2 CHAPTER IV : Combinatorial Optimization by Neural Networks 4.1. Combinatorial Optimization Problems The problems typically having a large but finite set of solutions among which we want to find the one that minimizes or maximizes a cost function are often referred

~~Combinatorial Optimization by Neural Networks~~
The solution space, denoted S, is the finite set of all possible solutions. The cost function, denoted by g, is a mapping from the set of solutions to real numbers, that is, g S?R [Aarts and Korst 89]. In the case of minimization, the problem is to find a solution S* ? S, called globally-optimal solution, which satisfies SgS SS i i * =min

~~CHAPTER IV Combinatorial Optimization by Neural Networks~~
The output hiof each hidden unit iis then computed by applying the basis function G to this distance hi= G(di,?i) (9.1.2)

~~CHAPTER IX Radial Basis Function Networks~~
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